

YASNAC^{ERC}

SAFETY FUNCTION FOR EUROPE

PARAMETER TABLE

Motomah L106S

	Initial value	Changed value
SC 052 Jog (LNR) MAX. SPEED	2.000	1.666
SC 054 Jog (LINK) MAX. SPEED	2.000	1.666
SC 056 Jog (Safety) MAX. SPEED	2.500	1.666
SC 073 Jog operation SPEED LEVEL 4	3.000	2.500

Motoman L15S

	Initial value	Changed value
SC 052 JOG (LNR) MAX. SPEED	2.000	1.666
SC 054 JOG (LNK) MAX. SPEED	2.000	1.666
SC 056 Inguard-Safety MAX. SPEED	2.500	1.666
SC 073 Jog operation SPEED LEVEL 4	3.000	2.500

Motomaru L60S

	Initial value	Changed value
SC 052 JOG (LNR) MAX. SPEED	2,000	1,562
SC 054 JOG (LINK) MAX. SPEED	2,000	1,562
SC 056 Inguard-Safety MAX. SPEED	2,500	1,562
SC 073 Jog operation SPEED LEVEL 4	3,200	2,500

Motoman KIOS

	Initial value	Changed value	
SC 052 JOG (LNR) MAX. SPEED	2,000	→	1,666
SC 054 JOG (UNK) MAX. SPEED	2,000	→	1,666
SC 056 Inguard-Saftey MAX. SPEED	2,500	→	1,666
SC 073 Jog operation SPEED LEVEL 4	3,000	→	2,500
SC 202 Initial operation speed of the robot	0	→	1 (Note)

Note : TORSTEKNIK only.

Motomdn K6S / K6SB

	Initial value	Changed value
SC 052 Jog (LNR) MAX. SPEED	2,000	1,666
SC 054 Jog (LINK) MAX. SPEED	2,000	1,666
SC 056 Inguard-Safety MAX. SPEED	2,500	1,666
SC 073 Jog operation SPEED LEVEL 4	3,000	2,500
SC 202 Initial operation Speed of the robot	0	1 (Note)

Note: TORSTEKNIK only